#### Information Systems for the SPD Experiment

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### SPD as a Data Source

• First stage: polarized/unpolarized HI (up to Ca), polarized p-p, d-d



- protons and deutrons
  - $\sqrt{s} = 9.4 \text{ GeV}$
  - luminosity up to  $10^{31} cm^{-2} s^{-1}$
  - $\sqrt{s} = 4.5 \text{ GeV/nucleon}$
  - luminosity up to  $10^{30} cm^{-2} s^{-1}$
- Interaction rate: up to 0.4 MhZ
- Number of channels: 177 K
- SPD Designed to operate at high luminosity but low track multiplicity
- High event rate, no simple signatures  $\Rightarrow$  Triggerless DAQ
- Event rate: up to 300 KhZ
- Online filter x20  $\Rightarrow$  15 kHz
- Events per year: up to 100 bn

- Raw data flow: up to 1 GB/s
- Duty cycle 0.3  $\Rightarrow$  10 PB/year

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• Online filter x20  $\Rightarrow$  0.5 PB/year

## SPD as a Data Source

#### • Second stage stage: polarized p-p, d-d



• protons and deutrons

- $\sqrt{s} = 27 \text{ GeV}$
- luminosity up to  $10^{32} cm^{-2} s^{-1}$
- $\sqrt{s} = 13.5 \text{ GeV/nucleon}$
- luminosity up to  $10^{31} cm^{-2} s^{-1}$

• Interaction rate: up to 4 MHz

- Num. channels: 283 or 608 K
- SPD Designed to operate at high luminosity but low track multiplicity
- High event rate, no simple signatures  $\Rightarrow$  Triggerless DAQ
- Event rate: up to 3 MHz
- Online filter x20  $\Rightarrow$  150 kHz
- Events per year: up to 1 tn

- Raw data flow: up to 20 GB/s
- Duty cycle  $0.3 \Rightarrow 200 \text{ PB/year}$
- Online filter x20  $\Rightarrow$  10 PB/year

Image: A matrix and a matrix



• Preparation for the experiment. MC Simulation: 2 PB per year. Total per stage: 10 PB.

- Stage I: Low lumi. MC and real data: 4 PB/y. Reprocessing: 2 PB/year. Total: 18 PB.
- Upgrade of the setup. MC simulation: 2 PB/y. Reprocessing: 2 PB/year. Total: 8 PB.
- Stage II: Max lumi. MC and real data: 20 PB/y. Reprocessing: 10 PB/y. Total: 120 PB.

#### Total for all stages: 156 PB.

Image: A matrix and a matrix

# SPD Information Systems

#### Data

- Distributed Computing and Data Management
- EventIndex
- Production and versions registry

#### Collaboration

Personnel and Publication Databases

#### Detector

- Hardware and Mapping Database
- Geometry registry
- Magnetic field maps registry
- Monitoring Information Systems
- Logging and Bookkeeping

### Distributed computing and data management

- Number of events, amounts of data, comparable to the LHC experiments.
- Distributed computing systems will be used for processing of data.
- Already existing methods and proven ready-made solutions will be adapted.
- Computing Resource Information Catalog (CRIC): information about computing and storage resources, access protocols, entry points, etc...
- **PanDA** WFMS: manages data processing at the level of jobs (files), tasks (datasets) and chains of tasks
- **Rucio** DMS: Data management: dataset and file catalog, transfer and deletion tools, data integrity and data lifetime strategies
- FTS DTS: enables massive data transfers

 Identity and Access Management Service (IAM): stores user profiles, their roles and rights to perform certain actions

#### EventIndex

- SPD needs a tool to effectively access trillions of physics events.
- Event Index: Complete catalog of SPD events, real and simulated data

#### Event Index use cases

- Event picking: selecting by ID events in some format and processing version
- Searching, counting and selection if events based on some parameters
- Production completeness and consistency checks
- A prototype of storage and client for the EventIndex has been tested
- PostgreSQL DBMS is used for storage and processing of data
- Various methods were investigated to speed up writing data to the DB.
- The estimated data flow from 10s k up to 150 k events per second
- Using of asynchronous bulk loading showed sufficient performance
- EventIndex development will go on as data model will be defined

#### Hardware Database

- A catalog of hardware components that SPD detector consist of.
- It should contain the information about the detectors and the electronic parts, as well as the location history of all items
- It include equipment models, provider, parameters and other (semi)permanent characteristics
- This should help in maintenance of the detector systems and especially helpful in knowledge transfer between team members.
- Filling of the hardware database should take place gradually, and updates will be rare
- The requirements for the speed of recording information in the database are low, as well as for reading of data
- The system should be tailored for the needs of the hardware development and maintenance

### Hardware Database: architecture

- A prototype system is being developed
  - PostgreSQL for a data storage
  - Back-end providing endpoints for access through the REST API
  - Web front-end providing interface for fill, search and display data
  - JINR SSO for authorization, access can be requested from web front
- The architecture of the project is built on the basis of microservices
- A stack of modern platforms is used to ensure good performance, flexibility and ease of development and maintenance



#### Hardware Database: interface

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JINR, Dubna. 2025												

- Development of the HW database is put on hold, no urgent demand
- Developers shifted to other projects with higher priorities

#### Hardware Database: interface

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JINR, Dubna. 2025										

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### Registries

- Development of the SPD software and ongoing large scale production campaign requires creation of a number of databases.
  - Production registry
  - Software version registry
  - Geometry registry
  - Magnetic field map registry

#### Common features

- These are quite small projects, should be available fast
- No high loads expected
- Low update frequency
- Payloads are normally stored separately, in files or sqlite
- Have to be developed independently, but need for data exchange may arise
- Similar platforms should be used to simplify development and maintenance
- IAM should be used for authentication and access management

#### Production

- Production of Monte-Carlo data started from March 2025 on a regular basis
- New production appear twice a week
- 2-steps: simulation + reconstruction



- More than 400M events produced, 200TB of data
- Production requests had different parameters:
  - Numbers of events (from 5M to 40M), software versions, production seeds, energy, polarization, detector configuration, etc...
  - Production scripts names and paths, output datasets names, etc..
  - Need a database to keep records of the production
- More production campaigns will be held
- More production steps will be added, parameter list may be changed
- Real data for some detectors (BBC) may appear this year!

## Production registry

- A prototype of the production registry has been created
- Expected to be filled by 2-3 responsible persons
- Will be used by all members related to the analysis and production
- Employs a framework fwkweb, similar to one used in CRIC

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- Production record contains name, description, software version, number of requested events, initial seed and processing types.
- On the second stage of development automatic generation of the production tasks specification may be implemented

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- For every processing type (simu, reco...) location of the macros are specified, as well as output datset templates and names.
- On the second stage of development automatic generation of the production tasks specification may be implemented

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# Software Versions registry

• Registry will keep information on versions of software used

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- Contains software tags, packages used, version descriptions links to the repositories, configuration an condition data compatibilities
- Will be filled by the person responsible for the deployment of the software frameworks (SPDRoot, SAMPO)
- Will be available through GUI and endpoints for use from other ISs

#### Geometries registry

- The GeoModel class library, which is presently in use by both the ATLAS and FASER experiments, will be used for the SPD detector description
- Geometry will be held held as a single file, should be used by a dedicated SAMPO framework tool
- DB record: tag for a geometry, version, metadata, link to a file on the cvmfs
- Metadata content should be defined lately

#### Magnetic field maps registry

- B-field maps, each having few GB in size will be held in a sqlite DB.
- Updates should be quite rear, few times a year
- DB record: tag for a map, its version, metadata, pointer to the map
- A special tool for SAMPO is being created to access B-field map, it will define metadata for the field maps and how it should be accessed.

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#### Further development

- Development of the B-field and geometry registries
- Application of the Hardware database to the actual needs of the detector and computing systems
- Development of the mapping database
- Development of the Condition and calibration databases
- Introduction of modern DevOps practices (CI/CD, etc...)

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