# Genetic Algorithm for determination of event collision time and particle identification by Time-Of-Flight at SPD NICA

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#### Task and initial conditions

Using information about particles trajectories and hits from TOF detector determine time of *pp*-collision.

- In this work only tracks with momentum below 500 MeV will not be considered.
- **2** Resolution of TOF detector  $\sigma_t = 70 \ ps$ .
- **1** Momentum resolution:  $\frac{\sigma_p}{p} = 2\%$
- TOF radius is 1 m and length of 3.772 m.

#### Plan of simulation

- **9** Get tracks of charged particles with momentum over 500 MeV from Pythia8 events with  $\sqrt{s} = 27$  GeV.
- 2 Calculate intersection point with TOF detector( $t_i$ ).
- **3** Calculate arc length of trajectory( $L_i$ ).
- Smear  $t_i$  with  $N(t_i, 70 ps)$  and  $p_i$  with  $N(p_i, 0.02 \cdot p_i)$ .
- **1** Using information about arc lengths of trajectories, TOF hits and particle momentum determine time of pp-collision( $t_0$ ).

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#### Brute force

How brute force works:

**①** Choose particles types to make tof hypotheses  $\rightarrow [\pi^{\pm}, K^{\pm}, p^{\pm}]$ .

$$tof_{ik} = \frac{L_i}{c} \sqrt{1 + \frac{m_k^2}{p_i^2}} \tag{1}$$

- For every event check all tracks hypotheses combinations 3<sup>N</sup> variants.
- **3** On every step calculate  $t_0$  and  $\chi^2$  and find  $\chi^2_{min}$ .

$$\chi^{2} = \sum_{i}^{N} \frac{(t_{0} + tof_{ik} - t_{i})^{2}}{\sigma_{t}^{2} + \sigma_{p_{i}}^{2}}, \quad t_{0} = \frac{1}{\omega} \sum_{i}^{N} \frac{t_{i} - tof_{ik}}{\sigma_{t}^{2} + \sigma_{p_{i}}^{2}}, \quad \omega = \sum_{i}^{N} \frac{1}{\sigma_{t}^{2} + \sigma_{p_{i}}^{2}}$$
(2)

**1** Time complexity  $O(N \cdot 3^N)$ .

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(2)

• Time complexity  $O(N \cdot 3^N)$  - very slow!!!

## Genetic algorithm

How genetic algorithm works:

- **①** Create population of random candidate solutions  $v([m_i]_k)$ .
- ② Create mutant vector from random candidates in population(DE-inspired):

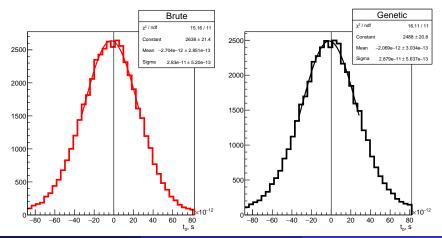
$$v_{mut} = v_r + v_p - v_q \tag{3}$$

- **3** Check if  $\chi^2_{mut} < \chi^2_r$  then replace  $v_r$  with  $v_{mut}$ . If not, population remains unchanged **Darwinian selection**.
- Repeat
- $\textbf{ § After some number of steps stop and choose } \chi^2_{\textit{min}} \text{ as an answer.}$
- Time complexity  $O(N \cdot N_{population} \cdot N_{steps})$ , 800 <  $N_{steps}$  < 1000.

## Genetic algorithm vs Brute force

- Brute force gives solution with minimal  $\chi^2$ , but very slowly.
- Genetic algorithm has less accuracy, but much faster.

Comparison of 2 algorithms was done on events with number of tracks 4 < N < 15.



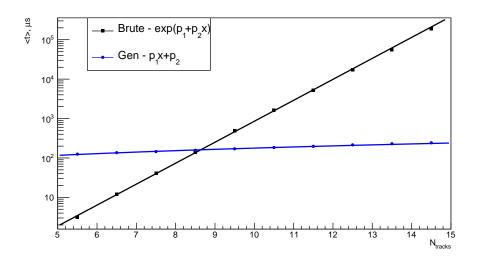
## Genetic algorithm vs Brute force

- **9** Brute Force resolution of  $t_0$  is 28 ps and Genetic Algorithm is 29 ps.
- PID event efficiency for Brute Force is 66.7% and for Genetic algorithm it is 63.3%.
- PID track efficiency for Brute Force is 97.2% and for Genetic algorithm is 96.8%.

PID event efficiency - percentage of events where all tracks were guessed correctly.

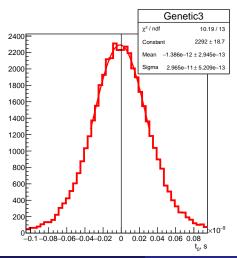
PID track efficiency - percentage of tracks that were guessed correctly.

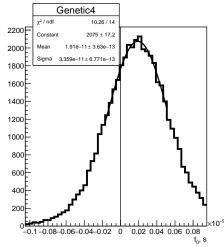
## Time complexity



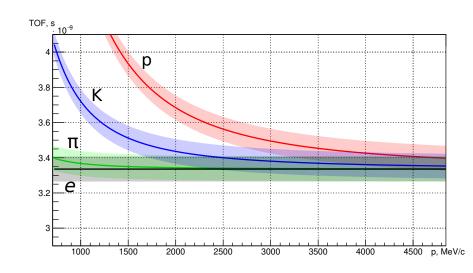
### Different hypotheses

Genetic3 hypotheses is  $[\pi^{\pm}, K^{\pm}, p^{\pm}]$ Genetic4 hypotheses is  $[e^{\pm}, \pi^{\pm}, K^{\pm}, p^{\pm}]$ 





## TOFs



#### Particle Identification

Some possible strategies:

- Take particles types from  $\chi^2$  minimum,
- Bayesian approach,
- N-sigma criteria.

In 2 and 3 strategies we exclude particle from determination of  $t_0$  to avoid correlations.

Bayesian approach	N-sigma criteria
$P(H_i \vec{S}) = \frac{P(\vec{S} H_i)C(H_i)}{\sum_{k=\pi,K,p}P(\vec{S} H_k)C(H_k)}$ $P(S  H_i) = \frac{1}{\sqrt{2\pi}\sigma_i} \exp\left(-\frac{1}{2}n_{\sigma_i}^2\right)$	$n_{\sigma_k^i} = rac{S_i - \hat{S}_i(m_k)}{\sigma_k^i}$
$P(S  H_i) = \frac{1}{\sqrt{2\pi}\sigma_i} \exp\left(-\frac{1}{2}n_{\sigma_i}^2\right)$	If $n_{sigma} < 3$ for certain type,
Probability of being particle	we associate this type with particle
of certain type	ightarrowmore than $1$ type

https://indico.jinr.ru/event/2788/contributions/15415/attachments/11871/19723/26.01.2022\_Ivanov.A.V.pdf

## Bayesian approach

Bayes formula:

$$P(H_i|\vec{S}) = \frac{P(\vec{S}|H_i)C(H_i)}{\sum_{k=\pi,K,p} P(\vec{S}|H_k)C(H_k)}$$
(4)

 $C(H_i)$ -prior probability,  $P(H_i|\vec{S})$  - posterior probability, which is calculated iterativly. On first step  $C(H_i)$  are chosen flat.

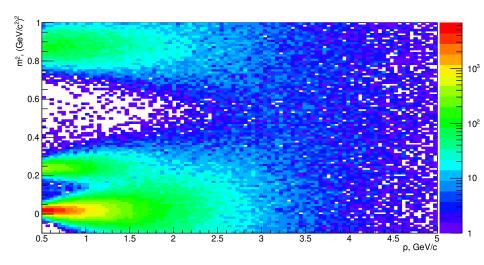
Detector signal:

$$P(S|H_i) = \frac{1}{\sqrt{2\pi}\sigma_i} \exp\left(-\frac{1}{2}n_{\sigma_i}^2\right)$$
 (5)

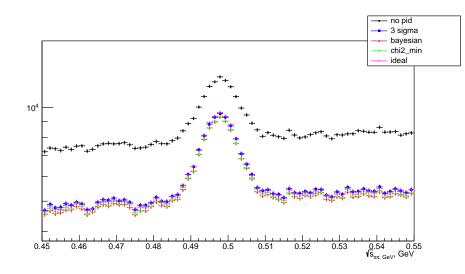
In case of multiple signal (i.e dE/dx + TOF):

$$P(S|H_i) = \prod_{k=dE/dx, TOF} P(S|H_i)_k$$
 (6)

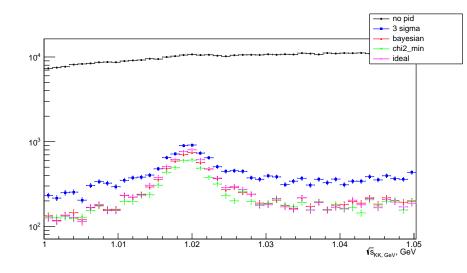
#### PID masses calculated with exclusion



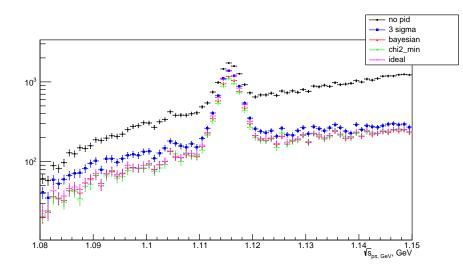
## Signals: $K_s$



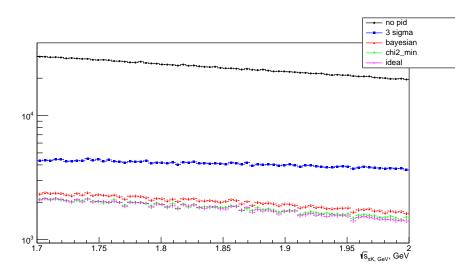
## Signals: $\phi$



## Signals: A



# Signals: $D^0$



## Summary

- 1 In events with low multiplicity (4 < N < 15) Brute Force on average spend 5 ms per event, and Genetic algorithm 0.160 ms.
- Quantime grows slowly as function of multiplicity for Genetic algorithm.
- **3** Brute Force resolution of  $t_0$  is 28 ps and Genetic Algorithm is 29 ps.

#### Outlook

- Ompare DE-inspired algorithm with other types of Genetic algorithms.
- Optimise Genetic algorithm to decrease run time.
- **1** Include  $t_0$  determination algorithm in SPD ROOT.
- PID procedure needs futher studies.

## Thank you for your attention!